StackADrop: A Modular Digital Microfluidic Biochip Research Platform

Advances in microfluidic technologies have led to the emergence of *Digital Microfluidic Biochips* (DMFBs), which are capable of automating laboratory procedures in biochemistry and molecular biology [4]. These devices use *electrowetting on dielectric* (see [6]) to move small volumes of liquids in order to perform experiments.

In the last years, DMFBs raised significant attention in industry and academia creating a demand for readily available devices. Commercial products are available but come at a high price and are usually designed for few procedures only. So far, there are two open hardware DMFBs available: the *DropBot* from WheelerLabs [3] and the *OpenDrop* from GaudiLabs [1].

The aim of the StackADrop was to create a device with many directly addressable cells while still being very compact. To make the StackADrop as easy to assemble as possible, the droplet moving technique used is the single-plate configuration (see e.g. [5]).

The StackADrop strives to provide simple means to experiment with different hardware setups. The main feature for that are the exchangeable top plates. They support up to 256 highvoltage pins via four 64-pin rows at the edges. Furthermore, the StackADrop has SPI, UART and I2C connectors that allow to easily attach sensors or actuators to the device. Furthermore, a SWD debugging port is provided. StackADrop can be connected to a computer using USB if more computational power is required or for interactive sessions using a control software.

One use case of the modularity of the StackADrop is to easily analyze and test different cell shapes, such as the conventional squares, hexagons (see e.g. [8]) and triangles (proposed in [2]). Top plates for these shapes (see Fig. 2) have been manufactured and will be used to check theoretical results from [2] and [7].

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Fig. 1. View of the StackADrop DMFB prototype



Fig. 2. StackADrop with three different PCB plates: squares (top), hexagons (left) and triangles (right)

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